

Midterm #2 Review

April 22, 2026

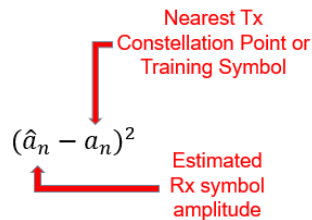
Notes by Jenna May

General course objectives

- Intuition for signal processing concepts
- Quantify design tradeoffs in signal quality vs. runtime complexity

Signal Quality Measures

- SNR = signal power / noise power
 - Thermal noise modeled as Gaussian random process in rx analog rf front end
 - Quantization noise modeled as uniform in the quantizer in an A/D converter
- PAM/QAM bit rate: $J f_{\text{sym}}$
- PAM bit rate $\propto Q(C_0 \sqrt{\text{SNR}})$
- PAM error vector magnitude²



- Objective function captures all the impairments in the error term $(\hat{a}_n - a_n)$
- Adapt subsystem parameters (e.g. FIR channel equalizer coefficients) to minimize the objective function – works well during training where we know a_n

Building Blocks

□ Signals

Impulse
Sinusoids
Exponentials
Rectangular Pulse
Triangular Pulse
Sinc & Raised Cosine
Chirp
Pseudo-noise
Impulse train
Noise

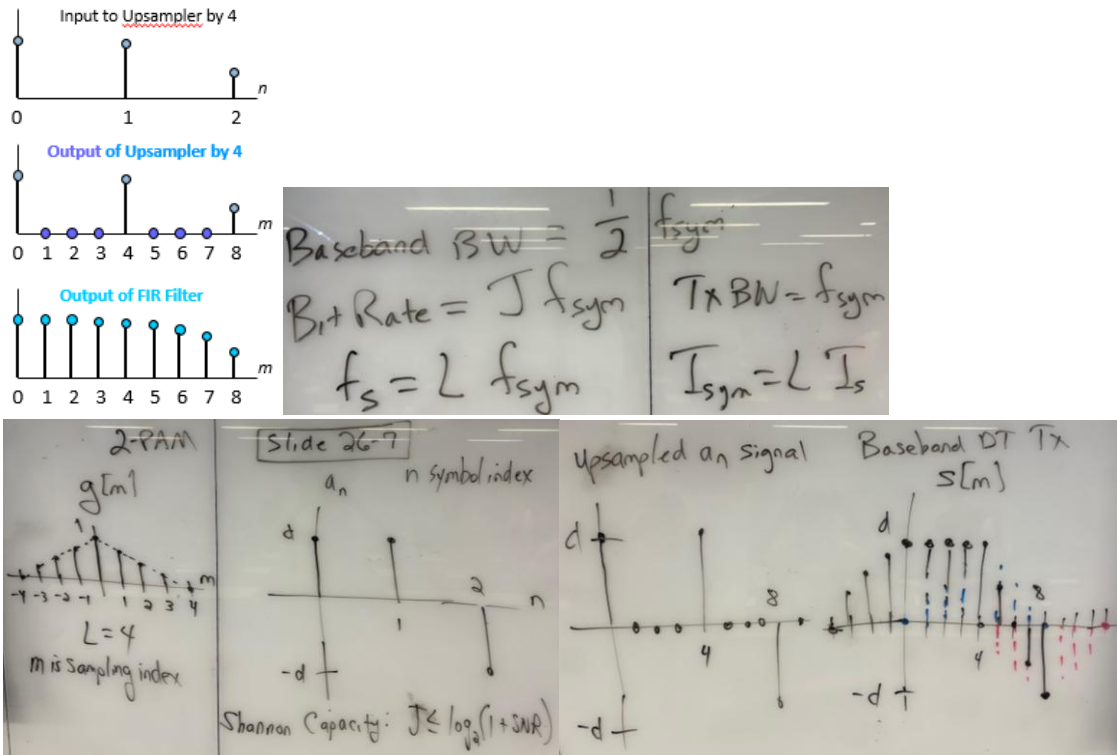
□ Systems

Adder & gain/multiplier
Ideal delay
FIR & IIR filters
Pointwise nonlinearities
(*squarer, absolute value, etc.*)
Signal generation (*sinusoidal*)
Samplers & up/downsampling
Quantizers
Modulators/demodulators
Adaptation (*steepest descent*)
Fast Fourier transform

Increasing the Sampling Rate

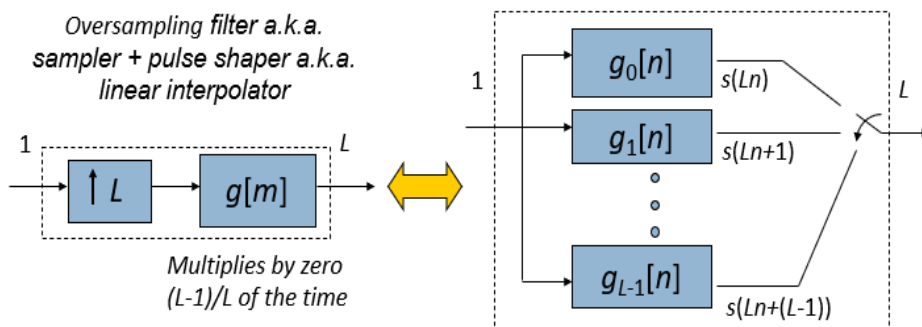
- Interpolation: upsampling by L followed by an interpolation FIR filter $g[m]$
- Upsampler copies an input sample to the output and inserts L-1 zero values; repeat
 - Increases the sampling rate by a factor of L
 - Output contains L-1 high-frequency replicas of the input signal

- Interpolation FIR filter $g[m]$
 - LPF with **bandwidth π/L** to **remove high frequencies** introduced by upsampling
 - Having every L th sample of $g[m]$ be zero keeps the input values to the upsampler unchanged and fills in the inserted zero values with something reasonable
- In a baseband PAM/QAM transmitter
 - L is the number of samples in a symbol period
 - Upsampling by L increases the sampling rate from the symbol rate f_{sym} to the D/A sampling rate f_s .
 - The interpolation FIR filter $g[m]$ is the pulse shaping filter to enforce the baseband bandwidth



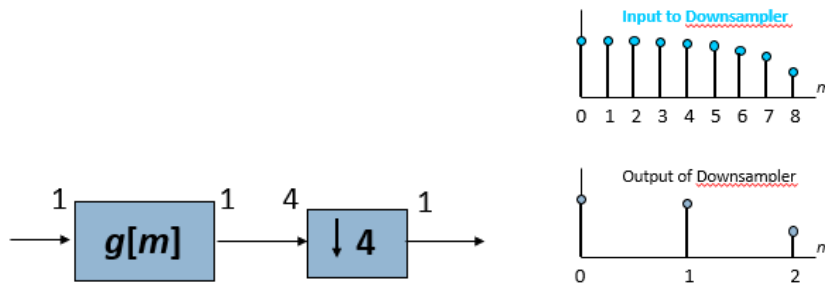
Polyphase Filterbank

- Avoids multiplications in the interpolation filter by the zeroes inserted by upsampling
 - **Saves factor of L** in multiplications and input storage
- **Split $g[m]$ into L shorter polyphase filters** operating at the lower sampling rate

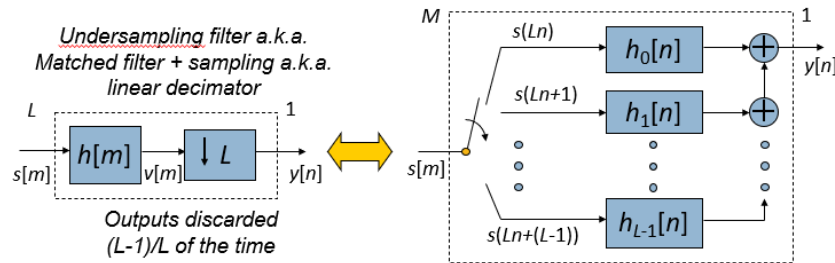


Decreasing sampling rate

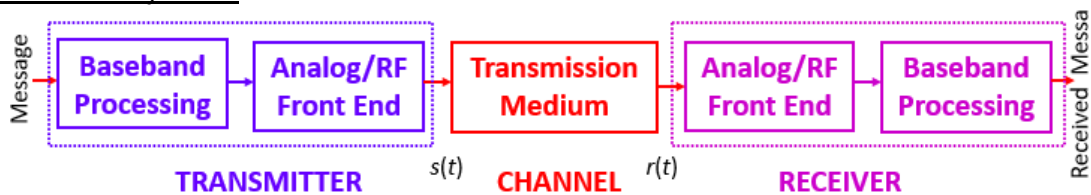
- Decimation: decimation FIR filter $g[m]$ followed by downsampling by L
- Decimation FIR filter is an anti-aliasing lowpass filtering to enforce the Sampling Theorem due to downsampling
 - **Bandwidth: π/L**
- Downsampling **outputs first sample and discards $L-1$ input samples**
 - Decreases input sampling rate by factor of L on the output
- In a baseband PAM/QAM receiver,
 - L is the number of samples in a symbol period
 - Downsampling by L decreases the A/D sampling rate f_s to the symbol rate f_{sym}
 - Decimation FIR filter $g[m]$ is the matched filter to enforce baseband bandwidth



- Can implement as polyphase filterbank



Communication Systems



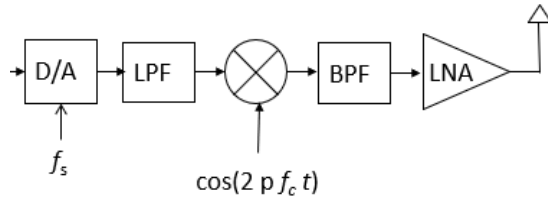
Transmitter

- Baseband message signal is information to be sent: voice, data, etc.
- Tx BB processing includes lowpass filtering to enforce transmission band
- Tx analog/RF front end includes **DAC, analog/RF upconverter, and transmit filter**

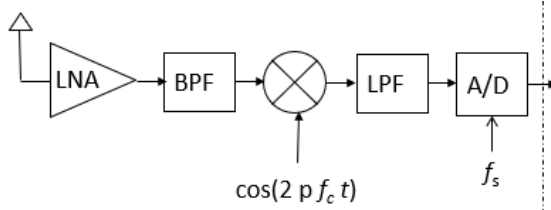
Receiver

- RF analog/RF front end includes **receive filter, carrier recovery, analog/RF downconverter, automatic gain control, ADC.**
- BB processing extracts and enhances BB signal

Tx Analog/RF

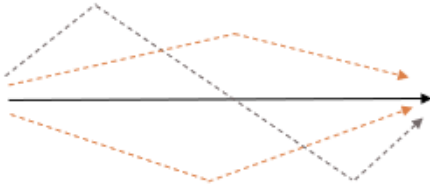


Rx Analog/RF Front End

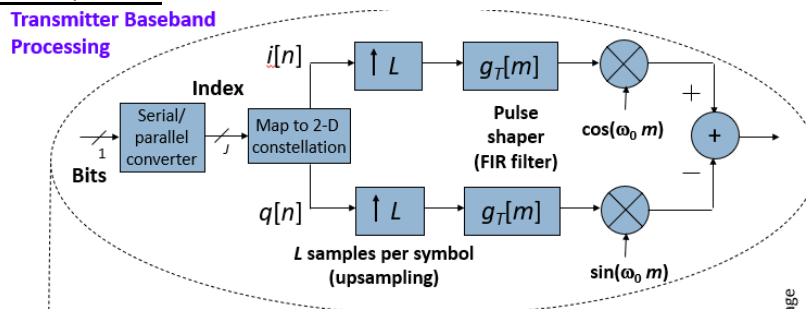


Channel Modeling

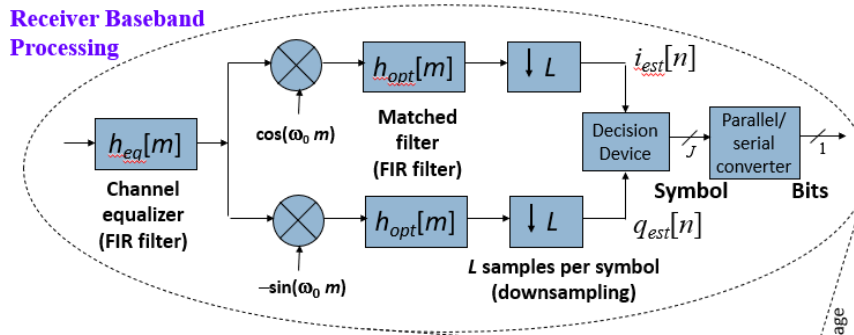
- Electromagnetic propagation of transmitted waves to the receiver
- Each path from tx to rx will have a different attenuation and delay
 - Distance traveled" $d = c \cdot \text{delay}$ where c is the speed of light [m/s]
 - Delay: d / c
 - Attenuation: d^{exp} where exp is between -3 and -4. In a vacuum, $\text{exp} = -2$.



Baseband QAM Tx



Baseband QAM Rx



QAM Signal Quality

- Assumptions
 - Each symbol is equally likely
 - Channel only contains AWGN, noise power $2\sigma^2$
 - Carrier frequency and phase recovery
 - Symbol timing recovery
- **Probability of symbol error for 16 QAM**

$$P(e) = 3Q\left(\frac{d}{\sigma}\sqrt{T_{sym}}\right) - \frac{9}{4}Q^2\left(\frac{d}{\sigma}\sqrt{T_{sym}}\right)$$

$$\frac{d}{\sigma}\sqrt{T_{sym}} \text{ is proportional to } \sqrt{\text{SNR}}$$

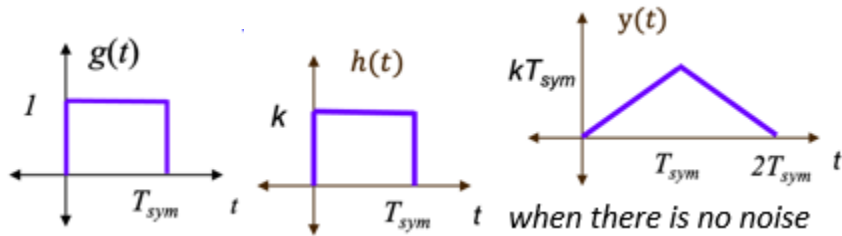
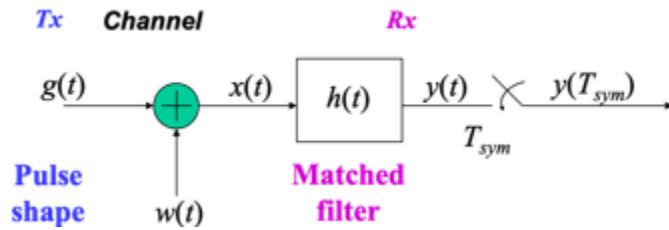
Communication System Tradeoffs

- How are parameters affected if only parameter in first column **increases**?
 - Blank means no effect
- Tip to check understanding: explain justification behind each answer

Parameter	Transmission Bandwidth	Bit Rate	Symbol Error Rate	Tx Power Consumption	Run-Time Complexity
B bits in A/D output & D/A input		?	?		increase
2d constellation spacing in Volts			decrease	increase	
f_{sym} symbol rate in Hz	increase	increase	increase		increase
J bits/symbol		increase	increase	increase	increase
L samples/symbol			decrease		increase
N_g symbol periods in pulse shape			decrease		increase

Symbol Timing Recovery

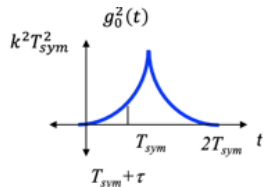
- Use matched filter to find **time τ of peak symbol power**



- Develop **adaptive method** to update τ in n th symbol period
- Maximize objective function $J = \frac{1}{2} y^2(t)$

$$y(t) = \underbrace{g(t) * h(t)}_{g_0(t)} + \underbrace{w(t) * h(t)}_{n(t)}$$

Where



and $n(t)$ is gaussian random signal with mean 0 and var

σ^2/T_{sym}

$$\tau[n+1] = \tau[n] + \mu \left. \frac{d}{d\tau} J(y(nT_{sym} + \tau)) \right|_{\tau=\tau[n]}$$

$$\tau[n+1] = \tau[n] + \mu y(nT_{sym} + \tau[n]) \left. \frac{d}{dt} y(t) \right|_{t=nT_{sym} + \tau[n]}$$